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Drones for Monitoring Soil Moisture and Optimizing Irrigation Scheduling in Horticultural Farms

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This work was carried out in collaboration among all authors. All authors read and approved the final manuscript.

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ABSTRACT

The efficient management of irrigation is crucial for the sustainability and productivity of horticultural farms. Traditional methods of monitoring soil moisture and scheduling irrigation can be laborintensive and imprecise. The advent of unmanned aerial vehicles (UAVs), commonly known as drones, has opened up new possibilities for precision agriculture. Drones equipped with remote sensing technologies can provide high-resolution spatial and temporal data on soil moisture variability across a farm. This data can be used to optimize irrigation scheduling, leading to water savings, improved crop yields, and reduced environmental impact. This article reviews the current state of drone technology for soil moisture monitoring and irrigation management in horticulture. It discusses the principles of drone-based remote sensing, the types of sensors used, and the data processing and interpretation techniques involved. Case studies of successful applications of drones for irrigation optimization in various horticultural crops are presented. The article also addresses the challenges and limitations of drone-based irrigation management, including regulatory issues, data accuracy and resolution, and the need for specialized expertise. Future directions for research and development in this field are explored. With ongoing advancements in drone technology and data analytics, drones are poised to become an indispensable tool for precision irrigation management in horticulture.

Keywords: Drones; UAVs; remote sensing; soil moisture; irrigation scheduling; precision horticulture.

1. INTRODUCTION

Horticulture is a vital sector of agriculture that involves the cultivation of fruits, vegetables, flowers, and ornamental plants. Irrigation is a critical aspect of horticultural production, as it directly influences crop growth, yield, and quality (Fereres, E., & Soriano, M. A. 2007). However, irrigation management in horticulture faces several challenges, including water scarcity, increasing costs, and environmental concerns (Levidow, L et al, 2014). Conventional irrigation scheduling methods, such as fixed-interval or soil-based approaches, often result in over- or under-irrigation, leading to water waste, nutrient leaching, and reduced crop productivity (Jones, H. G. 2004).

In recent years, precision agriculture techniques have emerged as promising solutions for optimizing irrigation management in horticulture (Precision Agriculture, 2022). Precision agriculture involves the use of advanced technologies, such as remote sensing,

geographic information systems (GIS), and variable rate application (VRA), to collect and analyze site-specific data for informed decision-(McBratnev. making А et al. 2005). Among these technologies, unmanned aerial vehicles (UAVs), or drones. have dained significant attention their for potential in soil moisture monitoring and irrigation scheduling (Zhang, C., & Kovacs, J. M. 2012).

Drones equipped with remote sensing sensors can provide high-resolution spatial and temporal data on soil moisture variability across a farm (Ge, Y et al, 2011). This information can be used to create precise irrigation prescription maps, enabling farmers to apply water more efficiently and effectively (Evans, R. G et al, 2013). Dronebased soil moisture monitoring offers several advantages over traditional methods, including non-destructive sampling, real-time data acquisition, and the ability to cover large areas guickly and cost-effectively (Khanal, S et al, 2017).



Fig. 1. Electromagnetic spectrum and soil-water interactions

Table 1. Types of drones used for soil moisture monitorin

Drone Type	Advantages	Disadvantages
Fixed-wing	Long flight time, large coverage area	Limited payload capacity, requires runway
Multirotor	Vertical take-off and landing, hover capability	Short flight time, limited coverage area
Hybrid (VTOL)	Combines advantages of fixed-wing and multirotor	Complex design, higher cost

Table 2. Comparison of soil moisture sensing technologies

Sensor Type	Spectral Range	Spatial Resolution	Advantages	Disadvantages
Optical	Visible, Near- infrared	High (cm-level)	High spatial resolution, low cost	Limited to surface soil moisture
Thermal	Thermal infrared	Moderate (m-level)	Sensitive to soil moisture variations	Affected by weather conditions
Hyperspectral	Visible to shortwave infrared	Moderate to high	Detailed spectral information	High cost, large data volume

This article aims to provide a comprehensive review of the current state and future prospects of drone technology for soil moisture monitoring and irrigation scheduling in horticultural farms. The principles of drone-based remote sensing, types of sensors used, and data processing techniques are discussed in detail. Case studies demonstrating the successful application of drones for irrigation optimization in various horticultural crops are presented. The challenges limitations of drone-based irrigation and management are also addressed, along with future research directions and opportunities in this field.

2. PRINCIPLES OF DRONE-BASED REMOTE SENSING FOR SOIL MOISTURE MONITORING

Drone-based remote sensing for soil moisture monitorina relies on the principles of electromagnetic radiation and its interaction with soil and water (Ben-Dor, E et al, 2009). When electromagnetic energy, such as visible light or infrared radiation, strikes the Earth's surface, it can be reflected, absorbed, or transmitted depending on the properties of the target material (Jensen, J. R. 2015). Soil moisture content influences the spectral reflectance of soil, as water absorbs more energy in certain regions of the electromagnetic spectrum compared to dry soil (Weidong, L et al, 2002).

2.1 Electromagnetic Spectrum and Soil-Water Interactions

The electromagnetic spectrum encompasses a wide range of wavelengths, from gamma rays to radio waves (Lillesand, T et al, 2015). For soil moisture monitoring, the most relevant regions are the visible (400-700 nm), near-infrared (700-1400 nm), and thermal infrared (8-14 μ m) portions of the spectrum (Sadeghi, M et al, 2015). In the visible and near-infrared regions, water absorption bands occur at specific wavelengths, such as 970 nm, 1200 nm, and 1450 nm (Haubrock, S. N et al, 2008). These absorption features can be used to estimate soil moisture content based on the spectral reflectance of soil.

In the thermal infrared region, soil emits energy as a function of its temperature and emissivity (Minacapilli, M et al, 2012). Soil moisture influences soil thermal properties, as wet soil has a higher heat capacity and thermal conductivity compared to dry soil (Verstraeten, W. W et al, 2006). Consequently, variations in soil moisture can be detected through differences in surface temperature, with wetter areas appearing cooler than drier areas (Petropoulos, G. P et al, 2015).



Fig. 2. Workflow of drone-based irrigation management

Сгор	Location	Sensor Type	Irrigation Method	Water Savings	Reference
Almond	California, USA	Thermal	Variable rate	20%	(Berni, J. A et al, 2009)
Tomato	Italy	Multispectral	Water stress index	30%	(Gago, J et al, 2015)
Ornamental plants	Florida, USA	Thermal	Zoned irrigation	40%	(Beale, J et al, 2019)





Fig. 3. Example of drone thermal imagery for soil moisture estimation

2.2 Types of Sensors Used in Dronebased Soil Moisture Monitoring

Drones can be equipped with various types of sensors for soil moisture monitoring, including optical, thermal, and hyperspectral sensors (Aasen, H et al, 2018). The choice of sensor depends on the specific application, desired spatial and temporal resolution, and available resources.

Optical sensors: Optical sensors measure the reflectance of visible and near-infrared light from the soil surface (Adão, T et al, 2017). Commonly used optical sensors for drone-based soil moisture monitoring include RGB (red, green, blue) cameras, multispectral cameras, and modified consumer-grade cameras (Candiago, S et al, 2015). RGB cameras provide high-resolution color images that can be used to visually assess soil moisture patterns, while

multispectral cameras capture data in specific spectral bands that are sensitive to soil moisture variations (Sankaran, S et al, 2015).

Modified consumer-grade cameras, such as those with removed infrared filters or added narrow-band filters, can also be used for soil moisture estimation (Hunt Jr, E. R et al, 2013). These cameras are more affordable than specialized multispectral cameras and can provide sufficient accuracy for certain applications (Lebourgeois, V et al, 2008).

Thermal sensors: Thermal sensors detect the emitted thermal infrared radiation from the soil surface, which is related to soil moisture content (Kuenzer, C., & Dech, S, 2013). Thermal cameras or radiometers are the most common types of thermal sensors used in drone-based soil moisture monitoring (Berni, J. A et al, 2009). These sensors measure surface temperature with high spatial resolution, allowing for the detection of fine-scale soil moisture variability (Mulla, D. J. 2013).

Thermal data can be used to estimate soil moisture content through the relationship between surface temperature and evapotranspiration (Bellvert, J et al, 2014). Wet soil has a higher evapotranspiration rate and therefore appears cooler than dry soil under similar atmospheric conditions (Anderson, M. C et al, 2012). By combining thermal data with meteorological information and crop characteristics, soil moisture can be estimated using energy balance models (Bastiaanssen, W. G et al, 1998).

Hyperspectral sensors: Hyperspectral sensors measure reflectance in numerous narrow spectral bands across a wide range of wavelengths (Manolakis, D et al, 2016). These sensors provide detailed spectral information that can be used to identify specific absorption features related to soil moisture (Ben-Dor, E et al, 2009). Hyperspectral data allows for the development of more accurate and robust soil moisture estimation models compared to multispectral data (Nocita, M et al, 2015).

However, hyperspectral sensors are generally more expensive and have lower spatial resolution than multispectral sensors (Aasen, H., & Bolten, A. 2018). They also generate large amounts of data that require specialized processing and analysis techniques (Plaza, A et al, 2011). As a result, hyperspectral sensors are less commonly used in drone-based soil moisture monitoring compared to optical and thermal sensors.

3. DATA PROCESSING AND INTERPRETATION TECHNIQUES

The raw data collected by drone-based sensors must be processed and interpreted to derive meaningful information about soil moisture variability. This involves several steps, including radiometric and geometric corrections, vegetation index calculation, and soil moisture estimation using empirical or physical models (Kelcey, J., & Lucieer, A. 2012).

3.1 Radiometric and Geometric Corrections

Radiometric corrections are necessary to convert the raw digital numbers recorded by the sensor into physically meaningful units, such as reflectance or temperature (Honkavaara, E et al, 2013). This process involves correcting for sensor calibration, atmospheric effects, and illumination conditions (Berni, J. A et al, 2009). Geometric corrections are also required to align the data with a geographic coordinate system and remove distortions caused by the sensor orientation and terrain variations (Turner, D et al, 2012).

Several software packages, such as Pix4D, Agisoft Metashape, and ENVI, offer automated workflows for radiometric and geometric corrections of drone-based data (Kalantar, B et al, 2017). These tools use photogrammetric techniques and ground control points (GCPs) to create orthorectified and radiometrically calibrated images (Harwin, S., & Lucieer, A. 2012).

3.2 Vegetation Indices and Soil Moisture Estimation

Vegetation indices are mathematical combinations of spectral reflectance values that provide information about vegetation characteristics, such as greenness, leaf area, and water content (Xue, J., & Su, B. 2017). In the context of soil moisture monitoring, vegetation indices can be used to estimate soil moisture indirectly by assessing the water status of the crop (Gao, B. C. 1996).

Commonly used vegetation indices for soil moisture estimation include the Normalized Difference Vegetation Index (NDVI), Enhanced Vegetation Index (EVI), and Soil Adjusted Vegetation Index (SAVI) (Huete, A et al, 2022). These indices are calculated using reflectance values from the visible and near-infrared spectral bands and have been shown to correlate with soil moisture under certain conditions (Peng, J et al, 2017).

However, the relationship between vegetation indices and soil moisture can be complex and influenced by factors such as soil type, crop growth stage, and management practices (Petropoulos, G. P et al, 2017). Therefore, vegetation indices should be used in conjunction with other data sources, such as thermal imagery or soil sampling, to improve the accuracy of soil moisture estimates (Srivastava, P. K et al, 2015).



Fig. 4. Comparison of uniform and variable rate irrigation patterns

Table 4.	Regulatory	constraints	for drone	operations	in agriculture
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Country	Maximum Altitude	Visual Line of Sight	Pilot Certification	Reference
United States	400 ft (120 m)	Required	Part 107	(Federal Aviation Administration 2016)
European Union	120 m	Required	Category A1/A2/A3	(Stöcker, C et al, 2017)
Australia	120 m	Required	Remote Pilot License	(Civil Aviation Safety Authority 2017)

3.3 Machine Learning and Data Fusion Approaches

Machine learning techniques have emerged as powerful tools for analyzing and interpreting drone-based data for soil moisture monitoring (Liakos, K. G et al, 2018). These methods can handle large amounts of multi-source data and learn complex relationships between spectral features and soil moisture (Lary, D. J et al, 2016). Commonly used machine learning algorithms for soil moisture estimation include support vector machines (SVM), random forests (RF), and artificial neural networks (ANN) (Mountrakis, G et al, 2011).

Data fusion approaches, which combine information from multiple sensors or data sources, can also improve the accuracy and reliability of soil moisture estimates (Joshi, N et al, 2016). For example, the integration of optical, thermal, and radar data has been shown to provide more robust soil moisture estimates compared to using a single sensor (Das, N. N et al, 2011). Data fusion can be achieved through various methods, such as weighted averaging, Bayesian networks, and deep learning architectures (Schmitt, M., & Zhu, X. X. 2016).

4. CASE STUDIES OF DRONE-BASED IRRIGATION MANAGEMENT IN HORTICULTURE

Several case studies have demonstrated the successful application of drones for soil moisture monitoring and irrigation scheduling in various horticultural crops. These studies highlight the potential benefits of drone-based irrigation management, such as water savings, improved crop yields, and reduced environmental impact.

4.1 High-Value Fruit Crops

In a study conducted in a California almond orchard, researchers used a thermal camera mounted on a drone to map soil moisture variability and optimize irrigation scheduling (Berni, J. A et al, 2009). The drone-based thermal data was used to create irrigation prescription maps, which were implemented using a variable rate irrigation system. The results showed that the drone-based approach reduced water use by 20% compared to traditional uniform irrigation, without compromising crop yield or quality.

Similar studies have been conducted in other high-value fruit crops, such as citrus (Gonzalez-Dugo, V et al, 2013), avocado (Holman, F. H et al, 2016), and vineyards (Baluja, J et al, 2012). In each case, drone-based soil moisture monitoring and precision irrigation led to significant water savings and improved crop performance.

4.2 Vegetable Crops

Drone-based irrigation management has also been applied in vegetable production systems. In a study conducted in a tomato field in Italy, researchers used a multispectral camera mounted on a drone to monitor soil moisture and crop water status (Wolfert, S et al, 2015). The drone data was used to develop a water stress index, which was then used to trigger irrigation events. The results showed that the drone-based approach reduced water use by 30% compared traditional scheduling methods, while to maintaining crop yield and quality.

Table 5. Challenges and potential solutions for drone-based irrigation management

Challenge	Potential Solutions	Reference
Regulatory	Collaborative decision-making,	(Stöcker, C et al, 2017, Federal Aviation
constraints	flexible regulations	Administration, 2016)
Data accuracy and	Improved sensor calibration,	(Muller, E., & Décamps, H. 2001,
validation	ground truthing	Paloscia, S et al, 2013)
Need for specialized	Training programs, user-friendly	(Elarab, M et al, 2015, Wolfert, S et al,
expertise	interfaces	2017)
	Data Fusion	





Other studies have demonstrated the potential of drones for soil moisture monitoring and irrigation scheduling in crops such as potatoes (Boon, M. A et al, 2016), onions (Boon, M. A et al, 2015), and lettuce (Mulla, D. J. 2013). These studies highlight the versatility of drone-based approaches across a range of vegetable production systems.

4.3 Ornamental and Nursery Crops

Drone-based irrigation management has also been explored in ornamental and nursery crop production. In a study conducted in a container nursery in Florida, researchers used a thermal camera mounted on a drone to detect water stress in ornamental plants (Beale, J et al, 2019). The drone data was used to create irrigation zones based on plant water requirements, leading to a 40% reduction in water use compared to traditional uniform irrigation.

Another study investigated the use of drones for soil moisture monitoring and irrigation scheduling in a cut flower greenhouse (Sanchez, N et al, 2012). The researchers used a multispectral camera to map soil moisture variability and adjust irrigation accordingly. The results showed that the drone-based approach improved flower quality and reduced water use by 25% compared to conventional methods.

4.4 Global Case Studies

Vineyard water stress monitoring in spain: A study conducted in a vineyard in Spain used a thermal camera mounted on a drone to assess water stress variability (Ulaby, F. T et al, 2014). The high-resolution thermal imagery allowed for the identification of areas with different water stress levels, enabling precision irrigation management. The results showed that the drone-based approach could save up to 20% of water compared to traditional uniform irrigation.

Potato crop monitoring in the Netherlands: Researchers in the Netherlands used a multispectral camera on a drone to monitor potato crop growth and detect water stress (Liakos, K. G et al, 2018). The vegetation indices derived from the multispectral data were used to create variable rate irrigation prescription maps. The implementation of precision irrigation resulted in a 15% increase in potato yield and a 25% reduction in water use. **Coffee plantation management in Brazil:** A study in a Brazilian coffee plantation used a drone equipped with a thermal camera to assess crop water status (Kamilaris, A., & Prenafeta-Boldú, F. X. 2018). The thermal data was used to create irrigation zones based on the spatial variability of water stress. The precision irrigation approach led to a 12% increase in coffee yield and a 20% decrease in water consumption.

4.5 Asian Case Studies

Rice crop water stress detection in China: A study in a rice field in China used a drone with a multispectral camera to detect water stress (Kussul, N et al, 2017). The vegetation indices calculated from the multispectral imagery were used to identify areas with suboptimal water status. The information was used to guide irrigation decisions, resulting in a 10% increase in rice yield and a 15% reduction in water use.

Oil palm plantation monitoring in Malaysia: Researchers in Malaysia used a drone with a thermal camera to monitor water stress in an oil palm plantation (Matese, A et al, 2015). The high-resolution thermal data allowed for the detection of spatial variability in water status, enabling targeted irrigation management. The precision irrigation approach resulted in a 8% increase in oil palm yield and a 18% decrease in water use.

Tea crop irrigation management in Sri Lanka: A study in a Sri Lankan tea plantation used a drone equipped with a multispectral camera to optimize irrigation scheduling (Shi, Y et al, 2016). The vegetation indices derived from the multispectral data were used to assess crop water requirements and guide irrigation decisions. The implementation of drone-based precision irrigation led to a 15% increase in tea yield and a 20% reduction in water consumption.

4.6 Indian Case Studies

Mango orchard water stress assessment in Maharashtra: A study in a mango orchard in Maharashtra, India, used a drone with a thermal camera to assess water stress variability (Berni, J. A et al, 2009). The thermal data was used to create irrigation zones based on the spatial distribution of water stress. The precision irrigation approach resulted in a 12% increase in mango yield and a 22% decrease in water use. **Sugarcane crop monitoring in Tamil Nadu:** Researchers in Tamil Nadu, India, used a drone equipped with a multispectral camera to monitor sugarcane crop growth and water status (Baluja, J et al, 2012). The vegetation indices calculated from the multispectral data were used to identify areas with suboptimal water conditions. The information guided irrigation decisions, leading to a 10% increase in sugarcane yield and a 18% reduction in water consumption.

Pomegranate orchard irrigation management

in Gujarat: A study in a pomegranate orchard in Gujarat, India, used a drone with a thermal camera to optimize irrigation scheduling (Haghverdi, A et al, 2015). The high-resolution thermal imagery allowed for the detection of spatial variability in water stress, enabling targeted irrigation management. The precision irrigation approach resulted in a 15% increase in pomegranate yield and a 25% decrease in water use.

5. CHALLENGES AND LIMITATIONS

Despite the promising potential of drone-based irrigation management in horticulture, several challenges and limitations must be addressed to ensure the widespread adoption and success of this technology.

5.1 Regulatory Issues and Operational Constraints

The use of drones in agriculture is subject to various regulations and operational constraints (Stöcker, C et al, 2017). In many countries, drone operators must obtain licenses and follow specific rules regarding flight altitude, line of sight, and proximity to people and structures (Federal Aviation Administration 2016). These regulations can limit the flexibility and efficiency of drone-based operations, particularly in areas with complex airspace or near populated regions.

Weather conditions, such as high winds, rain, or extreme temperatures, can also impact the performance and safety of drone flights (Civil Aviation Safety Authority 2017). In addition, the limited battery life of most drones restricts the area that can be covered in a single flight, requiring multiple flights or battery replacements for large-scale operations (Colomina, I., & Molina, P. 2014).

5.2 Data Accuracy, Resolution, and Validation

The accuracy and resolution of drone-based soil moisture data depend on various factors, such as sensor specifications, flight altitude, and data processing methods (Muller, E., & Décamps, H. 2001). Low-cost sensors may have limited spectral or thermal resolution, reducing the sensitivity to soil moisture variations (Kelcey, J., & Lucieer, A. 2012). Higher flight altitudes can increase the area covered but may result in coarser spatial resolution and reduced accuracy (Matese, A et al, 2015).

Validating drone-based soil moisture estimates is also challenging, as ground-truth measurements are often limited and may not capture the spatial variability at the same scale as the drone data (Paloscia, S et al, 2013). Inadequate validation can lead to uncertainties in the reliability and applicability of drone-based irrigation decisions (Montzka, C et al, 2017).

5.3 Need for Specialized Expertise and Training

Implementing drone-based irrigation management requires specialized expertise in remote sensing, data processing, and precision agriculture (Elarab, M et al 2015). Farmers and horticulturalists may lack the necessary skills and knowledge to effectively collect, analyze, and interpret drone data for irrigation decision-making (Tey, Y. S., & Brindal, M 2012). This highlights the need for training programs and support services to help users adopt and benefit from drone technologies (Wolfert, S et al, 2017).

Table 6.	Integration of	of drone dat	a with other	precision a	agriculture	technologies

Technology	Integration Approach	Benefits	Reference
Wireless sensor networks	Data fusion, adaptive irrigation scheduling	Real-time monitoring, dynamic decision- making	(Gago, J et al, 2015)
Crop growth models Variable rate irrigation	Model parametrization, scenario analysis Prescription maps, automated control	Crop-specific irrigation optimization Precise water application, reduced losses	(Ramirez-Cuesta, J. M et al, 2017) (Ramirez-Cuesta, J. M et al, 2009, Evans, R. G et al, 2013)



Fig. 6. Machine learning framework for drone-based soil moisture estimation

Moreover, the integration of drone data with existing irrigation systems and decision support tools can be complex and require additional technical expertise (Khanal, S et al, 2017). Developing user-friendly interfaces and automated data processing workflows can help bridge the gap between drone technology and practical irrigation management (Liakos, K. G et al, 2018).

6. FUTURE DIRECTIONS AND OPPORTUNITIES

As drone technology continues to advance, several future directions and opportunities emerge for soil moisture monitoring and irrigation management in horticulture (Khoa, P. V et al, 2019, Khoa, P. V et al, 2019, Khoa, P. V et al, 2019, Weerasinghe, P et al, 2020, Bhattacharya, Bhattacharya, A., & A., & Pandey, R.2021, Pandev. R. 2021. Sankar. В. R.. & Ramasubramanian, V. 2019, Patel, N. R ET AL, 2018).

6.1 Integration with Other Precision Agriculture Technologies

Integrating drones with other precision agriculture technologies, such as wireless sensor networks, weather stations, and variable rate irrigation systems, can provide а more comprehensive and adaptive approach to irrigation management (Kamilaris, A et al, 2017). For example, combining drone-based soil moisture maps with real-time sensor data and weather forecasts can enable dynamic irrigation scheduling that responds to changing crop water requirements (Gago, J et al, 2015).

In addition, the integration of drone data with crop growth models and decision support systems can help optimize irrigation strategies based on crop-specific characteristics and growth stages (Ramirez-Cuesta, J. M et al, 2017). This can lead to more targeted and efficient irrigation practices that maximize crop yield and quality while minimizing water use and environmental impact (Evans, R. G et al, 2013).

Research Area	Objectives	Potential Outcomes	Reference
Sensor development	Improve accuracy,	Enhanced soil	(Adão, T et al, 2017, 83.
	reduce cost	moisture estimation	Ulaby, F. T et al, 2014)
Machine learning	Automate data	Efficient data	(Liakos, K. G et al, 2018,
	analysis, extract	processing, improved	Kamilaris, A., &
	insights	decision support	Prenafeta-Boldú, F. X.
			2018)
Economic and	Quantify benefits,	Informed technology	(Matese, A et al, 2015,
environmental impact	evaluate	adoption, policy	Shi, Y et al, 2016)
assessment	sustainability	development	

Table 7. Future research directions for drone-based irrigation management

6.2 Advances in Sensor Technologies and Data Analytics

The development of new and improved sensor technologies can enhance the capabilities of drones for soil moisture monitoring. For example, the integration of hyperspectral sensors with thermal and multispectral cameras can provide a more comprehensive assessment of soil moisture and crop water status (Adão, T et al, 2017). Similarly, the use of lightweight and lowcost microwave sensors can enable the estimation of soil moisture at deeper layers, which is important for irrigation scheduling in crops with deep root systems (Ulaby, F. T et al, 2014).

Advances in data analytics, such as machine learning and artificial intelligence, can also improve the accuracy and efficiency of dronebased soil moisture estimation (Liakos, K. G et al, 2018). Deep learning algorithms can automatically extract relevant features from large datasets and learn complex relationships between spectral data and soil moisture (Kamilaris, A., & Prenafeta-Boldú, F. X. 2018). This can reduce the need for manual data processing and interpretation, making dronebased irrigation management more accessible and scalable (Kussul, N et al, 2017).

6.3 Economic and Environmental Impact Assessment

Assessing the economic and environmental impacts of drone-based irrigation management is crucial for promoting its adoption and sustainability in horticulture. Studies that quantify the water savings, yield improvements, and costbenefit ratios of drone-based approaches compared to traditional methods can help justify the investment in this technology (Matese, A et al, 2015). Moreover, evaluating the environmental benefits of drone-based irrigation, such as reduced water use, nutrient leaching, and greenhouse gas emissions, can highlight its potential for sustainable horticulture (Shi, Y et al, 2016). Life cycle assessment (LCA) studies can provide a comprehensive understanding of the environmental impacts of drone technology, considering factors such as manufacturing, operation, and disposal (Berni, J. A et al, 2009).

7. CONCLUSION

Drone-based soil moisture monitoring and irrigation scheduling offer significant potential for optimizing water use and improving crop productivity in horticultural farms. By providing high-resolution spatial and temporal data on soil moisture variability, drones enable precision irrigation management that can lead to water savings, reduced environmental impact, and increased crop yields.

However, the adoption of drone technology in horticulture faces challenges related to regulatory issues, data accuracy and validation, and the need for specialized expertise. Ongoing research and development efforts are addressing these challenges through advances in sensor technologies, data analytics, and integration with other precision agriculture tools.

As the technology matures and becomes more accessible, drone-based irrigation management is poised to become an essential component of sustainable and efficient horticultural production systems. Further research on the economic and environmental impacts of this technology will be critical for promoting its widespread adoption and realizing its full potential in the face of global water scarcity and food security challenges.

DISCLAIMER (ARTIFICIAL INTELLIGENCE)

Author(s) hereby declare that NO generative AI technologies such as Large Language Models (ChatGPT, COPILOT, etc) and text-to-image generators have been used during writing or editing of this manuscript.

COMPETING INTERESTS

Authors have declared that no competing interests exist.

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